Index

3D coordinate systems  793
3D density  1028
3D ellipsoid model  303

A
absolute differences  354
abstract generalisation  586
acoustic packaging  1277
  multimodal segmentation  1279
  structure detection  1281-1282
  synchrony analysis  1286
acoustic segmentation  1280
acquisitions and collection development  168
action-augmented envisionments  325
activation response  1741
active stereopsis  72
activity systems  1430
Adaptive Neuro-Fuzzy Inference System (ANFIS)  1699, 1705-1706
Adaptive Slot Assignment Protocol (ASAP)  841
Adequate Yearly Progress (AYP)  1428
Ad-hoc On demand Distance Vector (AODV)  843
agricultural field  1051
allothetic information  1573
alpha period  1749
Ambient Intelligence (AmI)  321
Anatomically-Correct Testbed (ACT)  1120
Animal-Assisted Activities (AAA)  1410
Animal-Assisted Therapies (AAT)  1410
Ankle–Foot Orthosis (AFO)  1295
Ant Colony Optimization (ACO)  435, 437-438, 875
Art Gallery Problem  434-435
artificial attractive field  86
artificial immune system (AIS)  1729
artificial intelligence (AI)  316, 1020, 1662-1663, 1735
artificial muscle
  curved type  1191, 1193-1194
  McKibben type  1189
  twist type  1191
Artificial Neural Network-Markov Transition Matrix (ANN-MTM)  1699
Artificial Neural Networks (ANN)  621, 1663
Artificial-Neural-Tissue (ANT) controllers  503
artificial repulsive field  86
Artificial Second Order Neural Unit (ASONU)  624
artist robot  486
  image processing  493
  software architecture  489
  specifications  487
assistive robotics  1616, 1628
Association of Research Libraries (ARL)  186
asymmetrical dry friction  910
Augmented Reinforcement Learning (ARL)  1266
Autism Spectrum Disorder (ASD)  1416
Auto Configurable Robots for Social Services (ACROSS)  1234, 1237
auto docking module  899
Automated Guided Vehicles (AGV)  1012-1014
Automatically Deployed Communication Relays (ADCR)  123
automatic positioning  951
Automatic Relevance Determination (ARD) method  1690
Automatic Train Control (ATC)  773
Automatic Train Protection (ATP)  773
Autonomous Robot Manipulation (ARM)  1357
autonomous robots  350, 1382
  stereo vision  353
Autonomous Underwater Vehicle (AUV)  647, 649
Index

B
Backpropagation (BP) 1700
backstepping observer 684
base-line stereopsis 74
batch processing 1076
Battlefield Extraction-Assist Robot (BEAR) 1356
behavior conflicts 16, 21, 32
Berkeley Lower Extremity EXoskeleton (BLEEX) 1120
beta period 1749
binocular disparity 813
binocular robot vision system 815
bioinspired and biomimetic robotics 1616, 1633
biomedical engineering 1098
biorobotics 1613-1614, 1617, 1636
bipedal robots 712
blimp extraction 825
color threshold 827
PCA 825
blimp vision systems 823
blimp visual odometry 829
body language 296
identification 297-298, 309
body part segmentation 298
body pose classification 303
bootstrap learning 1257, 1260
Brain-Machine Interface (BMI) 1323
bug algorithm 895

c
Cabel-based parallel manipulators 1219
cable-based robot 1223
Cable-Driven Robotic Arm (CDRA) 537-538, 549
Cable-Driven Universal Joint (CDUJ) module 538-539, 555
camera model 1486, 1584
camera system 945
capstone experience 1103
cartesian coordinates 1485
caster walker (i-Walker) 1296
Center for Pre-College Programs (CPCP) 1096
Central Pattern Generators (CPG) 1200
Chaos theory 1014
chatbots 170
chemical adhesion 744
Chemical, Biological, Radiological, and Nuclear (CBRN) 1355, 1360
child-robot relationship 1413
chromosome syntax 237
circulation technology 181, 186
climbing angle 943
closed-form solution 1488, 1493
closed loop manipulator 590
cluster tools 971
cognitive robotics 317
collision free motion 239
collision-free paths 235
Combat Search and Rescue (CSAR) 1370
communal sharing 1359, 1371
Comprehensive Access to Printed Materials (CAPM) 185
computational thinking 198
Computer-Aided Design (CAD) 649, 708, 1178
Computer-Aided Engineering (CAE) 649
Computer Aided Surgery (CAS) 1116, 1123
Computer-Integrated Surgery (CIS) 1148, 1619
Computers As Social Actors (CASA) 1369
Concerns Based Assessment Model (CBAM) 1107
deflagration 956
connectivity maintenance 121
connectomapping 1730
Constructionism Theory 203
Constructivism Theory 202
Context-Free Grammar (CFG) 415
control algorithm 482
Control Area Network (CAN) 650
costmap 895
Coulomb friction 571
Current Off-The-Shelf (COTS) 1358
Cyber-Physical Systems 839-840

D
Database of Recorded American Music (DRAM) 1080
Davis Nonverbal States Scale (DNSS) 296, 298
decontamination graph 957
Defense Advanced Research Project Agency (DARPA) 1355
Degrees of Freedom (DoF) 304, 488, 590, 606, 609, 692, 696, 944, 1039, 1120, 1153, 1217, 1321
delaunay triangulation 302
demining 941
Department of Defense (DoD) 1152, 1355
depth maps computation 1468
design constraints 548
design criteria 940
design variables 548
Index

Destination Sequenced Distance Vector (DSDV) routing protocol 844
developmental learning 1328, 1332
Diagonal Recurrent Wavelet Neural Network (DRWNN) 1700
differential drive 881
diffuse radiation 1679
Digital Signal Processing (DSP) 965
digitization 180, 189, 1074, 1086
Direct Numerical Control (DNC) 375, 388
Discrete Wavelet Transformation (DWT) 1692
disparity energy model 813
Disparity Space Image (DSI) 354, 1468
displacement analysis 539-540, 542
disposal 942
Distributed Bees Algorithm (DBA) 450-451, 456, 469
Distributed Vision System (DVS) 1482-1483
domotics 927
Dudek's taxonomy 455
dynamic programming 284, 1472
Dynamic Source Routing (DSR) 843
dynamic spatial phenomena 334
Dynamic Time Warping (DTW) 284, 288
Dynamic Window Approach (DWA) 879, 895, 897

E

educational robotics 195-196, 199, 202, 206, 1443
competitions 199, 1448
learning experience 196
projects 200
summer camp 1445
electromagnetic propagation models 1537
electromyography (EMG) 1120
Electronic Data Interchange (EDI) 1079
Electronic Resource Management (ERM) 169
electrorheological fluid brakes (ERB) 1294
electrorheological fluids (ERF) 1292-1293
electrostatic adhesion 744
embodied intention 1341
Empirical Risk Minimization (ERM) 87
end-effector 944
engineering design cycle 212
equation of motion 583, 587, 590, 593
equivolumetric partition 546
Espresso Book Machine (EBM) 188
Eulerian ZMP Resolution (EZR) 712, 715
European Space Agency (ESA) 559
evaluation mechanism 242
Explosive Ordnance Disposal (EOD) 940, 945, 1354-1355, 1363, 1374, 1376, 1380
Extended Kalman Filter (EKF) 118, 392, 1576, 1579
Extra-Vehicular Activities (EVA) 559

F

feature extraction
v-disparity 358
festinating gait 1199, 1210
quantification 1203
Fiducial Localization Error (FLE) 1154, 1162
Field Programmable Gate Array (FPGA) 812, 815, 818
field robots 2
finite capacity PN 978
fitness function 238
Flexible Manufacturing Systems (FMS) 1012
force-closure analysis 543
force-closure condition 543
force-closure pose 543
Force-Position control 571
forward displacement analysis 540
forward kinematics 550
Free-Body Diagrams (FBD) 583
free looking behavior 1748
Fugl-Meyer Assessment (FMA) 1236
Fuzzy Associative Memory Matrix (FAMM) 1550-1551
Fuzzy Logic (FL) 1666, 1706
fuzzy neural networks 1671
fuzzy obstacle analysis 355
Fuzzy Systems (FS) 1667

G

garment alignment devices 38
Gaussian noise 119, 886, 891, 1490-1491, 1496-1497, 1751
Geminoid 1320
experiments 1322
General Auto Recharging Solution (GARS) 899, 903
generalised momentum 585
Generalized Delta Rule (GDR) 1665
Genetic Algorithms (GA) 229, 237, 239, 244, 463, 875, 1506, 1547, 1669, 1706
genetic operators 238
Geographic Adaptive Fidelity (GAF) 842
Geographic and Energy-Aware Routing (GEAR) 842
Geographic Information Systems (GIS) 318, 1445
event-based 318, 348
Geometrically Exact Dynamic Splines (GEDS) 1517
geometric relationships 1492
gesture recognition 284
gesture representation 283
Global Moment Magnitude Index (GMMI) 547
Global Positioning System (GPS) 821, 1020, 1445, 1653
Global Solar Radiation (GSR) 1678, 1693
Grammatical Evolution guided by Reinforcement (GER) 410
Graphic Processing Units (GPU) 352
graph search algorithm 894
Grashof's criterion 598
Ground-Penetrating Radar (GPR) 942
Ground Reaction Force (GRF) 726
Guaranteed-Time Slot (GTS) 841

H
hand-eye calibration 1484
haptic feedback 560
haptic interfaces 560
Hidden Markov Models (HMM) 283-284
Hierarchical Intersystem Mobility Agent (HIMA) 1648
hierarchical planning 1257, 1263
High-order Processing Unit (HPU) 624
holonomic drive system 885
Home Exploring Robotic Butler (HERB) robot 880
Horizontal Field of View (HFoV) 356
Human-Machine Coexistent System (HMCS) 1292
Human-Machine Collaborative Systems (HMCS) 1387
Human Motion Capture (HMC) 279
humanoid robots 708, 1331
military development 1356
Human-Robot Interaction (HRI) 296, 1255, 1271, 1319, 1354, 1358, 1421
Human Visual System (HVS) 1467
Hungarian method 1590
Hybrid Assistive Limb (HAL) 1121
Hybrid Intelligent Systems (HIS) 1670
hybrid locomotion 664
hybrid systems 1670
Hydropower Plant (HPP) 647
Hyper Frame Vision (HFV) 61

I
idiothetic information 1573
Image-Guided Surgery (IGS) 1149
impedance control 1222
Improvised Explosive Device (IED) 951, 1380
Independent Component Analysis (ICA) 1386
industrial robots 2, 1049
Infinite Impulse Response (IIR) 1703
inhibition response 1741
Inquiry-Based Learning (IBL) 209
Integrated Library Systems (ILS) 182
Intelligent Battery & Power System (IBPS) 885
intelligent passive legs 911
intelligent robotics 69
Intelligent Transportation Systems (ITS) 1012
intention estimation 1383
Interlaced Extended Kalman Filter (IEKF) 391
Interlaced Kalman Filter (IKF) 397
International Federation of Robotics (IFR) 1
International Service Robot Association (ISRA) 2
International Space Station (ISS) 502, 559
interpersonal synchrony 1197-1200, 1202-1207, 1209-1211
inverse displacement analysis 542
inverse kinematics 551

J
Jacobian matrix 588
Jointly Exhaustive and Pairwise Disjoint (JEPD) 327, 331
joints and movements 1213
lower limb 1216
spine 1217
upper limb 1214
joint space 942
Just Doesn't Look Right (JDLR) 1355

K
Kalman Filter (KF) 118, 369, 888, 1576
Kappa statistics 1103
Karush-Kuhn-Tucker (KKT) 87
kinematics analysis 549
kinetic energy 584, 698, 1061
kinetostatic equilibrium 542
Kruskal–Wallis chi-square test 1285

L
Lagrangian dynamics 584
Lagrangian equation 586
Lamarck effect 414
language learning 1334
Laplacian of Gaussian (LoG) 353
laser distance 1486
Laser Radar (LADAR) 877
3D Tilting 897
laser range finder 1583
lateral dynamic stability 684
Lateral Load Transfer (LLT) 684
lean library management 1081
Levenberg-Marquardt algorithm 625, 629
library automation
  history 166
  overview 179
library materials detection 181
Light Detection And Ranging (LIDAR) 845
Linear Discriminant Analysis (LDA) 1386
Linked Multi-Component Robotic System (L-MCRS) 1516
Local Access Networks (LAN) 393
localization 942
Loss of Load Probability (LOLP) 1704
Loss of Power Supply Probability (LPSP) 1702
Low-Power Wireless Personal Area Networks (LoWPAN) 842
Low Pressure Chemical Vapor Deposition (LPCVD) 972
Low-Rate Wireless Local Area Networks (LR-WPAN) 841
lunabotic excavator 501
  UB Excavator 502, 505
lunabotic mining competition 503
Lyapunov function 86
Lyapunov guidance vector field 122

M
magnetic adhesion 744
Magnetic-field Sensitive Elastomer (MSE) 1294
Magnetic Resonance Imaging (MRI) 1127, 1137
magnetorheological fluid brakes (MRB) 1294
magnetorheological fluid (MRF) 1293, 1299
manipulator arm 944
Markov Decision Processes (MDP) 15-16, 144, 250, 1266
  concurrent 18
  decentralized 143-144, 147, 160, 162
  multi-agent 149
  opportunity cost decentralized 149
  Parallel (P-MDP) 20
  partially observable 144, 1255, 1258, 1263
  three approaches 17
  vector valued decentralized 157
Markov localization 368, 370
Markov Transitions Matrices (MTM) 1689
Mars Exploration Rover (MER) 502
mass matrix 587
mathematical model 910, 964
maxillofacial surgery 1138
Mean Bias Error (MBE) 1690, 1694
Mean Relative Error (MRE) 1705
mechanical adhesion 746
mechanization 1051
mechatronical system 910
mechatronics 1037, 1042
design 743
medical manipulators
  automaticity 613
  joint category 609
medical robotics (medibotics) 1097, 1099, 1106, 1117
medical robots 639
  clinical prototype 643
  operation 639
messenger robot
  with conflicts 26
  without conflicts 24
Metric-Based Iterative Closest Point (MbICP) 394
Micro Electro Mechanical Systems (MEMS) 1603
micro-robots 1603
  self-assembly 1606
microtube 911
Minimally Invasive Surgery (MIS) 1116, 1123, 1150, 1618
Minimum Mean Square Error (MMSE) 396
mission-planning 229
Mobile Ad hoc NETwork (MANET) 392, 1534
Mobile Laboratory Model (MLM) 1645-1646, 1655
  prototype 1653
mobile platform 231, 943
mobile robotics 263, 366, 876
mobile robots (mobots) 435, 451, 1654
  localization 887
  off-road 684
mobility-constrained system 959
Modified Ashworth Scale (MAS) 1236
Moment Magnitude Index (MMI) 546
Monte-Carlo Localization (MCL) 368, 372, 885
motion-in-depth 816
motion peaks 1280
Motion Planning Problems (MPP) 226
Moving Obstacle Avoidance (MOA) 105
Multi-Layer Perception (MLP) 1687
Multi-Objective Evolutionary Algorithm (MOEA) 622
<table>
<thead>
<tr>
<th>Index</th>
</tr>
</thead>
<tbody>
<tr>
<td>Multi-Objective Genetic Algorithm (MOGA) 622</td>
</tr>
<tr>
<td>Multi-Objective Problems (MOP) 622</td>
</tr>
<tr>
<td>Multi-Robot Exploration (MRE) 1585, 1587</td>
</tr>
<tr>
<td>multi-robot localization 398</td>
</tr>
<tr>
<td>multi-robot systems 113</td>
</tr>
<tr>
<td>decentralized control 144, 149</td>
</tr>
<tr>
<td>Multi-Robot Task Allocation (MRTA) 451, 473, 838-839, 845, 851-852, 875</td>
</tr>
</tbody>
</table>

| N |
| National Circulation Interchange Protocol (NCIP) 182, 191 |
| Natural Orifice Transluminal Endoscopic Surgery (NOTES) 1177, 1600 |
| NeuroMate robot 1155 |
| neurorobotic model 1741-1743 |
| MultiHab 1744 |
| VisMotor 1750 |
| neurorobotics 1739 |
| New Jersey Core Curriculum Content Standards (NJCCCS) 1096-1097, 1101 |
| New Jersey Institute of Technology (NJIT) 1096 |
| Next Generation Technical Services (NGTS) 1075 |
| Nickel Metal Hydride (NiMH) cells 1037 |
| nonlinear optimization 1489, 1495 |
| non-planar workspace 1494 |
| Non-Visited Cuts List (NVCL) 440 |
| Numerical Weather Prediction (NWP) 1692 |

| O |
| objective function 548 |
| object recognition 54, 62, 65 |
| obstacle avoidance 352, 1548, 1551 |
| calibration 1562 |
| obstacle crossing |
| high speed 692 |
| low speed 675, 683 |
| occupancy probability 1581 |
| omni-directional drive 881 |
| OpenWHEEL 676 |
| Operating Room (OR) 1140, 1154 |
| Optical Character Recognition (OCR) 87 |
| optimal baselines 1025 |
| optimal mission planning 232 |
| optimization model 548 |
| optimization results 549 |
| Optimized Link State Routing (OLSR) 844 |

| P |
| Parallel Kinematic Manipulator (PKM) 1500 |
| configuration 1502 |
| Partially Observable Markov Decision Processes (POMDP) 144, 1255, 1258, 1263 |
| Particle Filter (PF) 119 |
| Particle Swarm Optimization (PSO) 229, 860, 1505 |
| passive stereopsis 72 |
| path generation 33, 124-125 |
| path planning 90, 107, 845, 847, 859, 867, 1531 |
| patrolling mobile robot 876 |
| Percolation 129 |
| perttri net modeling 977 |
| phase difference 1203 |
| Phase Locked Loop (PLL) 369 |
| photodynamic therapy 612 |
| Photovoltaic Grid-Connected Systems (PVGCS) 1706 |
| Photovoltaic Power Supply (PVPS) 1705 |
| photovoltaic (PV) systems 1662, 1693 |
| piezoelectric robot 912 |
| pipe-crawling robot 911 |
| pitch stability 696 |
| planar workspace 1494 |
| planning algorithms 1258 |
| Planning Domain Definition Language (PDDL) 252 |
| pneumatic adhesion 744 |
| pneumatics in harvesting 1056 |
| polygon space fill 446 |
| Port Wine Stains (PWS) 612 |
| pose estimation 60, 62, 65 |
| Position Sensitive Detector (PSD) 375-376 |
| potential energy 584 |
| potential field 963 |
| potential field path planning 894 |
| power assist wear |
| arm 1194 |
| elbow 1193 |
| glove 1193 |
| predictive control 664 |
| predictive modeling 1724 |
| Principle Component Analysis (PCA) 825, 1386, 1388, 1390, 1392-1393 |
| Probability Density Function (PDF) 55, 366, 395, 888, 1395 |
| product-of-exponentials formula 556 |
| Project-Based Learning (PBL) 209 |
| Proportional Integral Derivative (PID) 824 |
| PUMA560 232 |
Index

Q
quadripole programming 88
Quadrupole Resonance Sensors (QRS) 942
qualitative measure 546
Qualitative Spatial Reasoning (QSR) 315
Quality-of-Service (QoS) 841, 847
quantitative measure 545
Quasi-Monte Carlo Localization (QMCL) 887
quick change joint 948

R
Radial Basis Functions (RBF) 88, 1665, 1687, 1696
radio frequency 393, 1388
Radio Frequency IDentification (RFID) 181
ramification problem 333
Rapidly exploring Random Trees (RRT) 124, 1547
Readiness to Teach Questionnaire (RTQ) 1107
reality mining 1724
Real-time Control Policy (RCP) 986
Reasoning about Actions and Change (RAC) 316
Received Signal Strength Indicator (RSSI) 656, 1535, 1544
Recursive Least Square with Covariance Resetting (RLS-CR) 621
Reference Clearness Index (RCI) 1690
region segregation 44
regolith mining 514
rehabilitation robotics 1118, 1616, 1628
rehabilitation robots 1217
Reinforcement Learning (RL) 249, 253, 269, 411, 1257, 1266, 1517
Relational Reinforcement Learning (RRL) 251
Relevant Social Groups (RSG) 1300, 1311, 1318
Remote Center of Motion (RCM) 1132, 1153
Remotely Operated Vehicles (ROV) 648
representation mechanism 241
Request Tracker (RT) 1079, 1090
reshaping human intentions 1387
residency time constraints 972
Resolved Momentum Control (RMC) 710
resource conflicts 16, 21, 32
Resource Description and Access (RDA) 1089
Resource Description Framework (RDF) 1091
Resource-Oriented PN (ROPN) 970
Rhythmic Auditory Stimulation (RAS) 1199
robotic surgery 1118
robotic vision system 1521
image acquisition 1518
specifications
Robot Learning by Imitation (RLbI) 276
Robot Netowrk (RON) 712, 715
Robot Operating System (ROS) 876, 881, 895, 1268
robot orientation alignment 901
robot platooning 146
robot position alignment 900
robot tracker 394
Root Mean Square Error (RMSE) 90, 1161, 1690, 1694
Rubric for Classroom Observation (RCO) 1105

S
salience map 788
Scale Invariant Feature Transform (SIFT) 55
scheduling algorithm 1000
Scheduling by Edge Reversal (SER) 956-957
Science and Technology Studies (STS) 1301
Science, Technology, Engineering, and Mathematics (STEM) 1097, 1442
Search and Rescue (SAR) 113
multi-robot systems 113-114
multi-robot teams 114, 118
Second Order Polynomial Neural Networks (SOPNN) 629
self-calibration 1484
Sensoric Arm Master (SAM) 564
Sensor Protocols for Information via Negotiation (SPIN) 842
serial manipulator 588
service robots 1, 32, 226, 1049
    personal 2
Roomba 879, 899
Shared Cataloging Program (SCP) 1075, 1086
Short-Time Fourier Transform (STFT) 1335
Sigma-Pi Networks 624
Simultaneous Localization and Mapping (SLAM) 112, 391, 820, 845, 1260, 1572, 1597
    probabilistic 1575
    vision-based 1577-1579
sink decomposition 957
Sister Kenny Home Therapy System (SKOTEE) 1236
skid-steering 665
    non-symmetrical 669
Skin Conductance Responses (SCR) 1323
Social Identity for Desindividuation Effects model (SIDE model) 1303
social robotics 1235
social robots 275-276
solar constant 1674
solar radiation 1672
    conventional models 1673
    prediction and modeling 1682
solar tracker 1040
    design 1041
    program 1042
sonar sensor 1583
spatial computing 319, 344
spatial dynamics
    commonsense reasoning 336, 349
    commonsense notions 330
spatial inertia 332
speed control 235
Speeded up Robust Features (SURF) 55, 57
Spike-Timing Dependent Plasticity (STDP) 1745-1746
Stand-Alone Photovoltaic Power (SAPVP) 1705
Standard Interchange Protocol (SIP) 182
standards-based lesson planning 1101
static path planning 234, 695, 927, 1233
static pose 303
stereo algorithm 353
Stereotactic Body Radiotherapy (SBRT) 1136
Stereotactic Radiotherapy (SRS) 1136
Stereotactical Microtelemanipulator (SMOS) 1137
stereo vision 1461
stride interval 1203
structural optimization 1504
Structural Risk Minimization (SRM) 87
subsumption architecture 384
Sum of Absolute Differences (SAD) 351
Support Vector Machines (SVM) 86-87, 350-351, 1386
surgical robotics 1615, 1621
surgical robots - See robotic surgery.
SURV-TRACK 839, 845-846, 848-849, 851, 859, 867
swarm intelligence 378
swarm robotics 376, 450, 1603
    firefighting 956, 962
Sycophant Wireless Sensor Networks (SWSN) 115
Sycophant Wireless Sensors (SWS) 115, 120, 124
synchrony constraint 1741, 1743
system modeling 583

T
target pursuit 1548, 1550
    calibration 1561
task space 946
teacher professional development 1100
Technical Services (TS) 1073-1074
Telemedicine & Advanced Technology Research Center (TATRC) 1152
Telenoid 1320
    experiments 1325
telesurgery 1164
tension analysis 542, 546, 554
terrestrial radiation 1680
therapy robotics 1615, 1621
third order polynomial network 625-626, 630
Time Difference of Arrival (TDoA) 121
Time Division Multiple Access (TDMA) 841
time-of-flight (ToF) 58, 305
time-optimal planning 240
topological maps 1581
traversability estimation 350, 352, 362, 1473
Two Wheeled Mobile Robot (TWMR) 91
Typical Meteorological Year (TMY) 1689
Typical Reference Year (TRY) 1705

U
Understanding by Design (UbD) 1444
Unexploded Ordnance (UXO) 1354-1355, 1360
Uniform Resource Locator (URL) 1075
Index

Universal Mobile Telecommunications System (UMTS) 1648
Unmanned Underwater Vehicles (UUV) 648
Uranus robot 878, 883
user expectations 954

V
validity box 1024
Vector Field Histogram (VFH) 879, 895
vergence eye movement 813-814
Versatile Event Logic (VEL) 326
vibration driven-robots 911
vibration-driven system 910
virtual reality 571
visibility polygon 440
Vision-based Inference Software (VIS) 1382
vision-based learning 1257
Visited Cuts List (VCL) 440
visual action segmentation 1280
visual attention 795
visual localization 797
visual memory 791
3D 794
visual servoing controller 830
blimp control 824
Voice Activity Detection (VAD) 1280
Voronoi diagrams 1557, 1582, 1589
vortex method 744
adhesion 748

W
wafer sojourn time 989
Warfighter’s Associate (WFA) 1356
Watchman Route Problem (WRP) 434, 437
Wavelet Neural Network (WNN) 1700
Webots 964
wheel sensing 934
wide surfaces printing robot 475
components and integration 480
mechanical structure and kinematics 213, 477-478
Wilcoxon-Mann-Whitney rank sum test 1285
Winner-Take-All (WTA) 1748
wireless communication 1534
Wireless Local Area Network (WLAN) 377, 1543, 1646
workspace analysis 44, 544-546, 553, 555
workspace-based design optimization 537-538
workspace model 233-234, 1574
WorldCat Local (WCL) 1075, 1080
worm-like principle of locomotion 909
Worm-Like Robot (WLR) 909
locomotion 919
mathematical model 913
two-mass 913

Z
Zero Moment Point (ZMP) 708