Index

\mathbf{A} "all-of-Switzerland", case study 64 AA 112, 114, 120 action abilities (AA) 112 activation level 39 activity-travel patterns, simulate 36-56 adaptive cruise and crossing control (A3C) 218, 219 adaptive cruise control 221 adaptive cruise control (ACC) 247 agent, their environment 110 agent-based approach 328 agent-based ATFM simulations 360 agents, independent vs. cooperative 309 agents in freight transport 323-341 AI layer 93 airspace concept evaluation system (ACES) 360 air traffic control (ATC) 359 Air Traffic Control System Command Center (ATC-SCC) 359 air traffic flow management 357–381 air traffic flow management (ATFM) 358 ASEP 134, 135, 136

aspiration level 36, 38, 39, 43, 47, 48, 53, 54
asymmetric simple exclusion process (ASEP) 134
ATFM, intro 359
ATFM issues 361
ATFM simulation design 365
autonomous agent 110
autonomous intersection control 280–290
autonomous vehicle control and collaborative driving systems 241
autonomous vehicles 193
axial 170, 171

B

basic drivers 39 BDI model 350 Blue-Adler model 135

\mathbf{C}

CA models, validation and extension 140 cascading traffic for departure time selection 272 catastrophic failures, mitigating 206 CATFM concept of operations 363 cellular automata models 134

centroidal 170	G
closed traffic areas 236	gaskinetic models 134
cognitive behaviors 163 collaborative air traffic flow management (CATFM)	Gipps-Marksjös model 135
358	
collaborative driving 240–260	Н
collaborative driving agents design 247	Helbing-Molnar-Farkas-Visek (HMFV) model 155
computing times 64	herding 128, 153, 159
conflict-area exclusive (CAE) 231	heterogeneous environment (CT3) 225
congestion in a multi-agent system 1–35 cooperative adaptive cruise control systems (CACC)	HMFV 155, 156, 160, 161, 162
247	HMFV model 160
271	I
D	IE 112
DAI 94	IF 112 impact on driving behavior (CU2) 227
decision making process of agents 16	initial individual demand modeling 74
density waves 127	intelligent agent-based model for policy analysis
DEQSim 66, 67, 72, 73, 74, 75	of collaborative traffic flow management
deterministic, event-based queue-simulation (DE-	(IMPACT) 360
QSim) 66	intelligent traffic-control (ITC) systems 219
difference reward functions 265 distributed artificial intelligence (DAI) 94	intelligent transportation systems (ITS) 109
driver-assistance agent (DAA) 222	interaction mechanism 112 interactive features (IF) 112
driver-assistance perspective 233	intersection-control perspective 228
driver agent behavior 200	intersection agent (IA) 222
TO.	intersection control, managed 194
E	intersection exclusive (IE) 231
effectiveness (CT4) 225	intersection manager, removing 196
Egress from aircraft 145	intersection safety for autonomous vehicles 193–217
Egress from football stadium 146	ITS 109
EMIL project 98, 100	110 100
empirical traffic problems 1 environment model 111	J
environment zones 117	jamming 126, 150, 152
evacuations: empirical results 132	Janning 120, 130, 132
evolutionary algorithm, systematic relaxation 69	\mathbf{L}
experience-based learning 44	Lakoba-Kaup-Finkelstein (LKF) model 155
F	lane exclusive (LE) 231
r	lane selection congestion model 273
Federal Aviation Administration (FAA) 358	lane shared (LS) 231
FIFO 66	lattice-gas models 138
finer space discretization 143	learning agents for collaborative driving 240–260
first-in, first-out (FIFO) behavior 66 flocking/herding 159	learning to coordinate 282 LKF 155, 156, 161, 162, 163, 164
floor field CA 136	LKF 133, 130, 101, 102, 103, 104 LKF model 161
fluid-dynamic models 133	locomotion 178
force field 170	
Fukui-Ishibashi model 135	

M	privacy and anonymity (CL3) 228 probability collectives (PC) 283
macroscopic models 133 managed intersection control 194	R
market penetration (CE2) 226 Markov decision processes 246 Markov decision processes (MDP) 308 Markov queue parking network module 9 MAS approaches for traffic control 310 MAS simulation model, four modules 6 MATSim 57, 59, 60, 61, 62, 63, 64, 65, 66, 68, 69, 70, 72, 74, 75 MATSim-T 57, 57–78, 59, 60, 61, 62, 63, 64, 65, 69, 70, 72, 74, 75 mechanism design (CE1) 226	reinforcement learning 308 reservation-based intersection control 281 reward functions 264 reward maximization 266 RIS system evaluation 301 road-to-vehicle (R2V) communication 242 robotics layer 86, 88 route choice mechanisms 293 route information sharing (RIS) 291–306 router module 68
microscopic models 133 microscopic simulation engine (MSE) 115	S
microscopic simulation engine (MSE) 113 microscopic simulation model 311 microscopic traffic modelling 108–123 MSE 115 multi-agent based simulation (MABS) 343 multi-agent system (MAS) 1, 2 multiagent learning 281 multi agent micro-simulation 59 multiagent simulation 297 multi agent transport simulation (MATSim) 57 multinomial mixed logit models 7 N navigation process 178 non-compliant drivers 275	"social potential" 155 "social potential" models for modeling traffic 155–175 safety for autonomous vehicles 193–217 seek (flee)/pursue (evade) 165 simulating cognitive agents in public transport systems 176–192 simulating transport corridor choices 349 simulation engine controller (SEC) 116 single agent learning 281 SIRO 12 social-force model 138 social learning 45 SP 112 SP models 159 system in random order (SIRO) 12
on-line optimization approach 331	T
PA 112, 114, 120, 121 partially observable Markov decision processes	time allocation mutator 68 traffic congestion management 261–279 traffic engineering 224 traffic experiments 266 traffic flow model 293 traffic flow simulation 65 traffic light control, reinforcement learning 312 traffic regulations (CL2) 228 traffic safety (CT2) 224 traffic simulation applications 79–107 transaction cost theory 343 transactions costs in transport corridors 342–356 transport corridor components 345 TRASS 79–107 TRASS, using 95 TRASS agent model 84

TRASS concept 82 TRASS topography model 83

U

Upper Derwent Valley, Peak District National Park, case study 1–35 urban traffic control (UTC) 307 user acceptance (CU1) 227

\mathbf{V}

valuation-aware traffic control 218–239 vehicle-to-vehicle (V2V) communication 242 vehicle-to-vehicle (V2V) protocol 197 vehicle control 252 vehicle coordination 254 vehicle information and communication system (VICS) 292
vehicle routing problem 327
vehicle routing problems (VRPs) 324
vehicular sensors, intersection control 220

W

wall following 167, 168 wander 163, 165 wayfinding, computational models 182 wayfinding and locomotion 186

\mathbf{Z}

Zürich Regensbergbrücke, case study 183